Call for Papers

IEEE Transactions on Human-Machine Systems

Special Issue on:

"Holistic approaches for Human-Vehicle Systems: combining models, interactions and control"

Ground vehicles operate in a complex human—vehicle—road environment involving numerous levels of interaction among drivers, vehicles, and the ambient within which they travel. Human drivers may be "intelligent controllers" that define the intended driving direction and/or operate (totally or partially) autonomous vehicles. To support the development of safe driver-vehicle interactions in an era of increasing automation, methods for modeling and analyzing the contribution of driver performance are critical and essential. This raises interesting challenges associated with the characterization and modeling of human behaviors, particularly with respect to cognition and neuromuscular dynamics, their implication in closed-loop driver—vehicle performance, and their induced modifications brought about by interaction with the surrounding environment. Specifically, holistic approaches are of interest, which aim at efficiently and quantitatively combine different aspects of the human-vehicle interaction in specific application domains.

This special issue focuses on these relevant driver-vehicle interaction topics, with attention paid to the range of vehicles and associated technology currently on the market and emerging in the era of increased automation.

The topics of interest include but are not limited to:

- Modeling and characterization of driver-vehicle interactions
- Human driver modeling: neuromuscular dynamics, skills and learning
- Advanced vehicle control systems with driver-in-the-loop
- Intelligent and cognitive vehicles
- Advanced driver assistance systems (ADAS)
- Modeling and characterization of human drivers' errors
- Characterization and quantification of driver's capabilities

Important Dates:

Manuscript submission:

Completion of first round of reviews:

Revised manuscript submission:

Notification of final decision:

Final manuscript submission:

March 31, 2017

Paper should be submitted through http://mc.manuscriptcentral.com/thms, with a cover letter that contains the statement: "This manuscript is being submitted to the Special Issue: Modeling, Dynamics, Perception and Control of Human–Vehicle Systems". For detailed submission information, please refer to "Information for Authors" at http://ieee-smc.org/publications/thms-info-for-authors.pdf.

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